

## 12.1 Nondeterminism

The idea of “nondeterministic” computations is to allow our algorithms to make “guesses”, and only require that they accept when the guesses are “correct”. For example, a simple nondeterministic polynomial-time algorithm to decide whether a number  $N$  is composite would nondeterministically guess a factorization  $L, M$  of the number, and then verify that  $L \cdot M = N$ . (It turns out that there is also a deterministic polynomial-time algorithm for deciding compositeness, discovered in 2002, but it is much more complicated.)

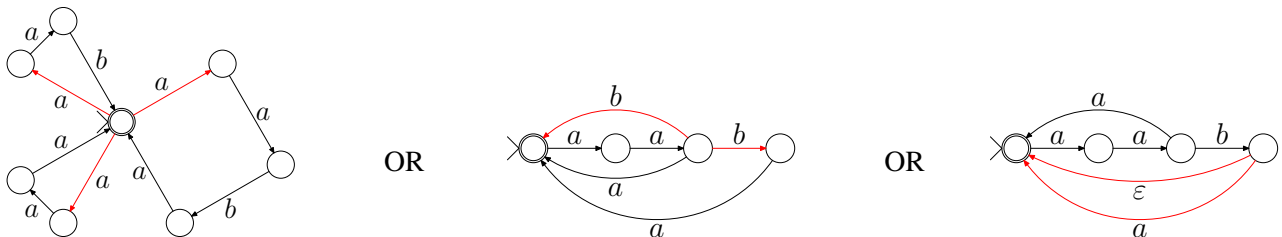
Nondeterminism is not a realistic or physical computational resource, but turns out to be very useful for capturing many computational problems of interest and better-understanding realistic deterministic models of computation. Just like introducing the imaginary number  $i = \sqrt{-1}$  turns out to be very useful in answering questions about the ordinary real numbers.

## 12.2 Nondeterministic Finite Automata

A language for which it is hard to design a DFA:

$$L = \{aab, aaba, aaa\}^* = \{x_1x_2 \cdots x_k : k \geq 0 \text{ and each } x_i \in \{aab, aaba, aaa\}\}.$$

But it is easy to imagine a “device” to recognize this language if there sometimes can be several possible transitions!



**Def:** An NFA is a 5-tuple  $(Q, \Sigma, \delta, q_0, F)$ , where

- $Q, \Sigma, q_0, F$  are as for DFAs
- $\delta : Q \times (\Sigma \cup \{\epsilon\}) \rightarrow P(Q)$ .

When in state  $p$  reading symbol  $\sigma$ , can go to any state  $q$  in the set  $\delta(p, \sigma)$ .

- there may be more than one such  $q$ , or
- there may be none (in case  $\delta(p, \sigma) = \emptyset$ ).

Can “jump” from  $p$  to any state in  $\delta(p, \epsilon)$  without moving the input head.

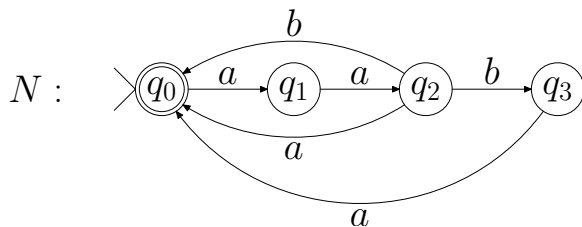
### Computations by an NFA

$N = (Q, \Sigma, \delta, q_0, F)$  accepts  $w \in \Sigma^*$  if we can write  $w = y_1 y_2 \cdots y_m$  where each  $y_i \in \Sigma \cup \{\epsilon\}$  and there exist  $r_0, \dots, r_m \in Q$  such that

1.  $r_0 = q_0$ ,
2.  $r_{i+1} \in \delta(r_i, y_{i+1})$  for each  $i = 0, \dots, m-1$ , and
3.  $r_m \in F$ .

**Nondeterminism:** Given  $N$  and  $w$ , the states  $r_0, \dots, r_m$  are not necessarily determined.

### Example of an NFA



$N = (\{q_0, q_1, q_2, q_3\}, \{a, b\}, \delta, q_0, \{q_0\})$ , where  $\delta$  is given by:

	$a$	$b$	$\epsilon$
$q_0$	$\{q_1\}$	$\emptyset$	$\emptyset$
$q_1$	$\{q_2\}$	$\emptyset$	$\emptyset$
$q_2$	$\{q_0\}$	$\{q_0, q_3\}$	$\emptyset$
$q_3$	$\{q_0\}$	$\emptyset$	$\emptyset$

### Tree of computations

Tree of computations of NFA  $N$  on string  $aabaab$ :

An NFA  $N$  accepts  $w$  if there is at least one accepting computation path on input  $w$ , so we could check all computation paths to determine whether  $N$  accepts  $w$ . But the number of paths may grow exponentially with the length of  $w$ ! Can the exponential search be avoided?

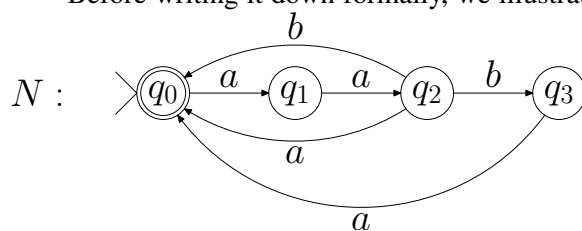
### NFAs vs. DFAs

NFAs seem more “powerful” than DFAs. Are they?

**Theorem 12.1** For every NFA  $N$ , there exists a DFA  $M$  such that  $L(M) = L(N)$ .

**Proof by Construction:** Given any NFA  $N$ , we construct a DFA  $M$  such that  $L(M) = L(N)$ . The idea is to have the DFA  $M$  keep track of the *set* of states that  $N$  could be in after having read the input string so far.

Before writing it down formally, we illustrate with an example. Recall our NFA  $N$  for  $L = \{aab, aaba, aaa\}^*$ .



$N$  starts in state  $q_0$  so we will construct a DFA  $M$  starting in state  $\{q_0\}$ :

## Formal Description of the Subset Construction

Given an NFA  $N = (Q, \Sigma, \delta, q_0, F)$ , we construct a DFA  $M = (Q', \Sigma, \delta', q'_0, F')$  where

$$\begin{aligned} Q' &= P(Q) \\ q'_0 &= E(\{q_0\}) \\ F' &= \{R \subseteq Q : R \cap F \neq \emptyset\} \text{ (that is, } R \in Q') \\ \delta'(R, \sigma) &= E(\{q \in Q : q \in \delta(r, \sigma) \text{ for some } r \in R\}) \\ &= \bigcup_{r \in R} E(\delta(r, \sigma)), \end{aligned}$$

where for a set  $S \subseteq Q$ ,  $E(S)$  is the set of states that can be reached starting from a state in  $S$  and following 0 or more  $\epsilon$  transitions.

It can be shown by induction on  $|w|$  that for every string  $w$ , running  $M$  on input  $w$  ends in the state  $\{q \in Q : \text{some computation of } N \text{ on input } w \text{ ends in state } q\}$ .

## Rabin & Scott, "Finite Automata and Their Decision Problems," 1959

1976 – Michael O. Rabin See the ACM Author Profile in the Digital Library

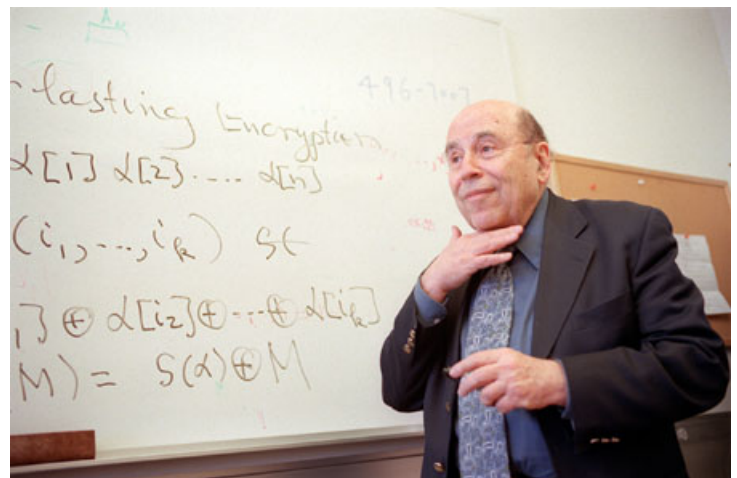
### Citation

For their joint paper "Finite Automata and Their Decision Problem," which introduced the idea of nondeterministic machines, which has proved to be an enormously valuable concept. Their (Scott & Rabin) classic paper has been a continuous source of inspiration for subsequent work in this field.

### Biographical Information



Michael O. Rabin (born 1931 in Breslau, Germany) is a noted computer scientist and a recipient of the Turing Award, the most prestigious award in the field.



## Using NFAs for Pattern Recognition

NFAs can express quite complicated pattern-recognition problems. Indeed, it is easy to construct an NFA  $N$  that accepts exactly the strings generated by any given *regular expression*, such as

$$R = ((a \cup b \cup c \cup \dots \cup z)^*(foo \cup bar)(a \cup b \cup c \cup \dots \cup z)^*(foo \cup bar))^* \cup (a \cup b \cup c \cup \dots \cup z)^*.$$

This regular expression  $R$  generates the set  $L(R)$  of strings over alphabet  $\Sigma = \{a, b, \dots, z\}$  that have an even number of non-overlapping occurrences of “foo” or “bar”. We can easily convert  $R$  (or any regular expression, for that matter) into an NFA  $N$  such  $L(N) = L(R)$ :

[The converse is also true (but harder to prove): for every NFA  $N$ , one can construct a regular expression  $R$  such that  $L(R) = L(N)$ . So DFAs, NFAs, and Regular Expressions all describe exactly the same set of languages! If you're interested in the full proof, see the recommended text by Sipser.]

So to decide whether a given string  $w \in \Sigma^*$  matches a given regular expression  $R$ , we can convert  $R$  to an NFA  $N$ , convert  $N$  to a DFA  $M$ , and then run  $M$  on  $R$ .

**Q:** What's the problem with this approach? How can we do better?

**Theorem 12.2** *Given an NFA  $N = (Q, \Sigma, \delta, q_0, F)$  and a string  $w$ , we can decide whether  $w \in L(N)$  in time  $O(|Q|^2 \cdot |w|)$ .*

**Proof:**