Role of Fiber Stitching in Eliminating Transverse Fracture in Cross-Ply Ceramic Composites

Tian-Jian Lu and John W. Hutchinson

Division of Applied Sciences, Harvard University, Cambridge, Massachusetts 02138

A theoretical study of the feasibility of using fiber stitching to prevent transverse matrix cracking in cross-ply ceramic composites is reported. The prototype problem solved is a curved composite beam subject to pure bending (the C-specimen), which develops a transverse tensile stress \( \sigma_t \) acting across its circumferential midplane. Fiber stitches normal to this plane bridge a circumferential matrix crack lying along the midplane of the specimen. Results are presented for the energy release rate of this matrix crack as a function of a nondimensional parameter characterizing the fiber stitches. Sufficiently large values of this parameter ensure the applicability of the classical ACK (Aveston, Cooper and Kelly) limit for a steady-state matrix crack subject to \( \sigma_t \). The results obtained can be used to choose the level of stitching such that transverse matrix cracking will be excluded.

I. Introduction

In this note, a plane strain curved beam of cross-ply ceramic laminate subjected to a bending moment \( M \) at the ends is considered, as shown schematically in Fig. 1(a) \( (M \) is defined per unit width perpendicular to the plane in this figure). The composite beam has inner and outer radii \( R_i \) and \( R_o \) with thickness \( H = R_o - R_i \). A moment with the sense of application shown induces a transverse (radial) tensile stress acting perpendicular to the circumferential planes. Let \( \sigma_t \) denote the transverse stress acting on the midplane lying halfway between the inner and outer radii, and let \( (\sigma_t)_{\text{max}} \) denote the maximum tensile circumferential stress which occurs at the inner radius. The ratio of \( \sigma_t \) to \( (\sigma_t)_{\text{max}} \) increases as \( R_i/R_o \) decreases, but is always much smaller than unity. For example, assuming material isotropy in the plane of the specimen, \( \sigma_t/(\sigma_t)_{\text{max}} = 0.051 \) for \( R_i/R_o = 4/5 \), 0.087 for \( R_i/R_o = 2/3 \), and 0.157 for \( R_i/R_o = 1/3 \). (A formula relating \( \sigma_t \) and \( M \) for the case of circumferential anisotropy is given by Lu et al.\(^\text{25} \).

Even though the transverse stress \( \sigma_t \) will be small compared to the stress acting parallel to the specimen, this transverse stress is cause for concern in an unstitched cross-ply, since there is no mechanism to arrest a matrix crack once one becomes critical (see Fig. 2). This has been verified by the analysis of the unbridged circumferential crack lying at the midplane between the inner and outer radii. The normalized energy release rate for an unbridged crack, \( G_o \), increases sharply as the subtending angle, \( 2\theta \), increases, as shown in Fig. 3. These results were taken from Ref. 2 and apply to the case of a cross-ply with isotropic elastic properties in the plane of the specimen, where \( E \) is the cross-ply modulus. The results in Fig. 3 imply that a small unbridged crack-like flaw will grow unstably to a significant length as soon as it becomes critical, as experiments on unstitched C-specimens reveal. Such a cross-ply would be unacceptably susceptible to transverse cracking and the ensuing loss of bending stiffness that would entail. Transverse cross-stitching is required to eliminate transverse matrix cracking, or, at least, to ensure that significant stiffness loss does not accompany transverse matrix cracking.

The problem addressed here is that of the circumferential crack in Fig. 1 bridged by transverse fiber stitches. There are two aspects to the problem. As might be surmised on intuitive grounds motivated by the depiction in Fig. 1(b), the classical ACK\(^{1-3} \) result for steady-state matrix cracking of a bridged crack applies to this problem if the stitching is adequate. The level of stitching required for applicability of the ACK formula will be obtained. Given this applicability, one can then predict the level of stitching needed to exclude transverse matrix cracking, if that is the objective.

Fig. 1. (a) Conventions for the curved composite beam with fiber stitching across the surfaces of a matrix crack. (b) “Steady-state” matrix crack propagating under stress \( \sigma_t \).
stitching fibers, which should be identified with the modulus of the cross-ply in the transverse (radial) direction, and

\[ E = c_1 E_t + (1 - c_1) E_c. \]

The problem of Fig. 1 with Eq. (1) specified along the crack has been analyzed using a finite element formulation, and results will be reported below. If the stitching meets the condition

\[ \frac{B \sqrt{H}}{\sqrt{E_c \sigma_0}} > 1 \]

it will be seen that the energy release rate \( G \) of the crack is well approximated by

\[ G_{\text{ACK}} = \frac{2 \sigma_0^2}{3 B^2} \]

This is the ACK prediction\textsuperscript{13} for the situation depicted in Fig. 1(b), where the bridged matrix crack responds to the local midplane stress \( \sigma_0 \) as if it were applied remotely to a straight semiinfinite bridged crack advancing in steady state in an infinite solid. Condition (3) ensures that the substantial crack opening, which would occur for the unbridged crack, will be suppressed by the stitching. This condition also ensures that the major stiffness loss accompanying an unbridged circumferential crack will largely be eliminated.

Continue to let \( G_0 = G (B = 0) \) be the energy release rate of the unbridged circumferential crack plotted in Fig. 3. The energy release rate \( G \) of the bridged circumferential crack shown in Fig. 1 can be expressed in either of the two following nondimensional forms:

\[ \frac{G}{G_0} = F_1 (\theta, B \sqrt{H} \sqrt{E_c \sigma_0}, R/R_o) \]

\[ \frac{G}{G_{\text{ACK}}} = F_2 (\theta, B \sqrt{H} \sqrt{E_c \sigma_0}, R/R_o) \]

where \( G_{\text{ACK}} \) is given by Eq. (4). There is also a dependence, not explicitly shown, on the Poisson ratio and on any nondimensional parameters characterizing elastic anisotropy of the crossply in the plane of the specimen. The numerical results reported below in Figs. 4 and 5 are restricted to the case of elastic isotropy in the plane with a Poisson ratio of 0.3.

A finite element procedure was used to obtain the crack tip energy release rate as dependent on the stiffness of the stitching fibers. Details of the finite element modeling are similar to those described for the unbridged crack in Ref. 2. The nonlinear bridging law (1) is implemented via the spring element provided in the finite element code ABAQUS. The energy release rate \( G \) at the tip of the circular matrix crack is calculated by applying an adaptation of the J-integral. A mesh sensitivity study was conducted to ensure the accuracy of the results reported below.

III. Results and Discussion

Figure 4 presents the results of the energy release rate as the ratio \( G/G_0 \) versus \( B \sqrt{H} \sqrt{E_c \sigma_0} \) for \( \theta = 30^\circ \) and for two inner-to-out radius ratios, \( R/R_o = 2/3 \) and \( R/R_o = 4/5 \). The results show that stitching reduces the energy release rate to a small fraction of the value for the unbridged crack for all values of \( B \sqrt{H} \sqrt{E_c \sigma_0} \) which are larger than about 0.5. These same results, along with an additional set of results for \( \theta = 10^\circ \), are plotted in Fig. 5 as the ratio \( G/G_{\text{ACK}} \). This plot reveals the approach of \( G \) to \( G_{\text{ACK}} \) as \( B \sqrt{H} \sqrt{E_c \sigma_0} \) increases. As a reasonable approximation, one can estimate \( G \) using \( G_{\text{ACK}} \) when condition (3) is met, and in essentially all cases \( G_{\text{ACK}} \) provides an upper estimate to \( G \). (The ratio \( G/G_{\text{ACK}} \) is zero at \( B \sqrt{H} \sqrt{E_c \sigma_0} = 0 \) because \( G = G_0 \) at \( B = 0 \), while \( G_{\text{ACK}} \) is unbounded as \( B \) approaches 0.)

To summarize, we consider the simultaneous implications of condition (3), guaranteeing the approximation \( G \approx G_{\text{ACK}} \), together with the requirement

\[ G_{\text{ACK}} < (1 - c_1) T_{\text{in}} \]
ensuring that transverse matrix cracking does not occur. Here, \( \Gamma_m \) is the effective toughness of the matrix material through which the transverse crack propagates. Condition (3) can be expressed as a requirement on the area fraction of stitching fibers as

\[
\frac{c_t}{1 - c_t} \geq \frac{E_t^2 \sigma_0 R_t}{4E_tE^2 \left( \frac{R_t}{\sqrt{E \sigma_0}} \right) / \tau} \tag{8a}
\]

Similarly, condition (7) can be expressed as

\[
\frac{c_t}{1 - c_t} \geq \sqrt{\frac{E_t^2 \sigma_0 R_t}{6E_tE^2 \tau (1 - c_t) \Gamma_m}} = \sqrt{\frac{E_t^2 \sigma_0 R_t}{4E_tE^2 \left( \frac{R_t}{\sqrt{E \sigma_0}} \right) / \tau} \sqrt{\frac{2\sigma_0^2}{3E_t(1 - c_t) \Gamma_m}}} \tag{8b}
\]

As an illustration, consider the following representative values: \( E_t = E_m = E = 200 \text{ GPa}, R_t = 7 \mu \text{m}, \) and \( \sigma_0 = 50 \text{ MPa}, \) and assume the area fraction of the fiber stitches is \( c_t = 0.05. \) Condition (8a), ensuring \( G = G_{ACK}, \) is satisfied for all levels of \( \tau \) to the right of the vertical dashed line in Fig. 6, corresponding to a particular value of specimen thickness \( H. \) Condition (8b), which excludes the possibility of matrix cracking, is independent of \( H \) and is met for all combinations of \( \tau \) and \( \Gamma_m \) above the solid line curve in Fig. 6. This example emphasizes that careful consideration may have to be given to the level of fiber stitching and the fiber–matrix interface properties if transverse matrix cracking is to be avoided. If one is willing to tolerate matrix cracking as long as there is not a major loss of bending stiffness, then one needs only to satisfy (8a). Finally, it has tacitly been assumed that the length of the sliding zone on either side of the matrix crack surface does not reach the inner or outer surfaces of the specimen (i.e., the sliding length is less than \( H/2 \)). This possibility can be checked, but it would be likely only for thin specimens with low levels of \( \tau. \)

Acknowledgments: The authors would like to thank Y. L. Cui, A. G. Evans, J. R. Rice, and Z. C. Xia for helpful discussions. The commercial finite element code ABAQUS was used in the numerical computation.

References